

$a_i^{(l)}$ ~ layer
 a_i ~ unit

activation

$$a_1^{(2)} = g(z_1^2)$$

$$z_1^2 = \theta_{10}^{(1)} x_0 + \theta_{11}^{(1)} x_1 + \theta_{12}^{(1)} x_2 + \theta_{13}^{(1)} x_3$$

$\theta^T \cdot x$



sig

$$= \frac{1}{1 + e^{-(\theta_{10}^{(1)} x_0 + \theta_{11}^{(1)} x_1 + \dots)}}$$

$$a_2^{(2)} = g(z_2^2)$$

$$= \frac{1}{1 + e^{-(\theta_{20}^{(1)} x_0 + \theta_{21}^{(1)} x_1 + \theta_{22}^{(1)} x_2 + \theta_{23}^{(1)} x_3)}}$$

$\downarrow$
 $z_1^{(2)}$

$$a_3^{(2)} = g(z_3^2) = \frac{1}{1 + e^{-(\theta_{30}^{(1)} x_0 + \theta_{31}^{(1)} x_1 + \dots)}}$$

$$\theta^{(1)} : [3 \times 4]$$

$$2 \quad \theta^{(1)} : [3 \times 4] \times [4 \times 1]$$

$$\underline{\underline{z}} = \underline{\underline{\Theta}} \underline{\underline{x}} = [3 \times 4] \times [4 \times 1]$$

$$= [3 \times 1]$$

$$a^2 = g(z^2) = \underline{\underline{[3 \times 1]}}$$

$$z^3 = \underline{\underline{\Theta}}^{(2)} \underline{\underline{a}}^2$$

$\downarrow$

$$[1 \times 4] [4 \times 1] = [1]$$

$$z^3 = \underbrace{\Theta_{10}^{(2)} a_0^2 + \Theta_{11}^{(2)} a_1^2 + \Theta_{12}^{(2)} a_2^2 + \Theta_{13}^{(2)} a_3^2}$$

$$\underline{\underline{a}}^3 = g(\underline{\underline{z}}^3)$$

$$= \underline{\underline{\quad \quad \quad}}$$

a_1^3

$$1 + e^{-\left(\theta_{10}^{(2)} a_0^{(2)} + \theta_{11}^{(2)} a_1^{(2)} + \dots\right)}$$

$$a_1^{(2)}$$

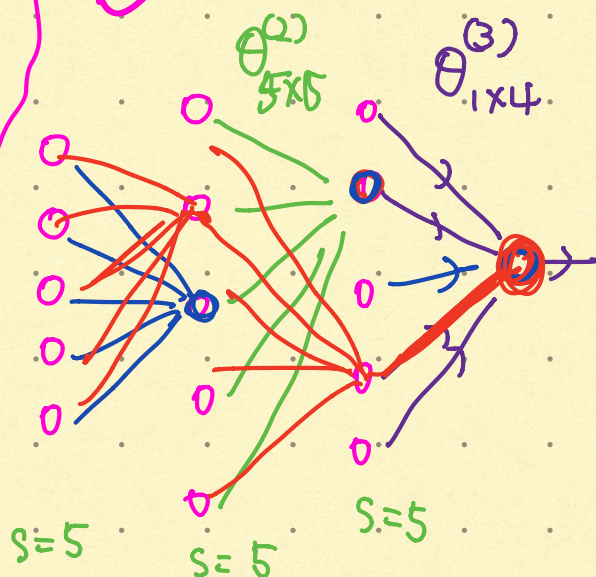
$$1 + e^{-\left(\theta_{10}^{(1)} x_0 + \theta_{11}^{(1)} x_1 + \theta_{12}^{(1)} x_2\right)}$$



$$z^{(l)} = \sum_k \theta_{jk}^{(l-1)} a_k^{(l-1)} + \theta_{j0}^{(l-1)}$$

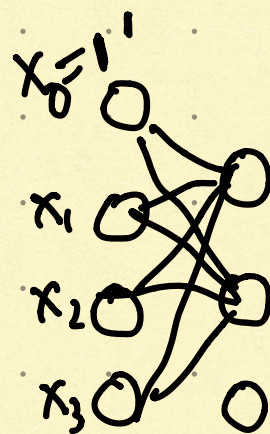
$$= \theta^{(l-1)} \underline{a}^{(l-1)}$$

$$a_j^{(l)} = g\left(\sum_k \theta_{jk}^{(l-1)} a_k^{(l-1)} + \theta_{j0}^{(l-1)}\right)$$



In a vector form

$$\begin{matrix} z^2 \\ 5 \times 1 \end{matrix} = \begin{matrix} \Theta^{(1)} \\ 5 \times 4 \end{matrix} \begin{matrix} a^1 \\ 4 \times 1 \end{matrix}$$



$$\Theta^{(1)}_{[5 \times 4]} = \begin{bmatrix} \theta'_{10} & \theta'_{11} & \theta'_{12} & \theta'_{13} \\ \vdots & \vdots & \vdots & \vdots \\ \theta'_{50} & \theta'_{51} & \theta'_{52} & \theta'_{53} \end{bmatrix} \quad \begin{matrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{matrix}$$

$\frac{1}{1 + e^{-z_5^2}}$

$$a^2 = g(z^2) \quad 5 \times 1 \rightarrow (a_0^2, a_1^2, a_2^2, \dots, a_5^2)$$

$\frac{1}{1 + e^{-z_1^2}} \quad \frac{1}{1 + e^{-z_2^2}}$

$$\begin{matrix} z^3 \\ 5 \times 1 \end{matrix} = \begin{matrix} \Theta^{(2)} \\ 5 \times 6 \end{matrix} \begin{matrix} a^2 \\ 6 \times 1 \end{matrix}$$

$$\Theta^{(2)} = \begin{bmatrix} \theta_{10}^2 & \theta_{11}^2 & \dots & \theta_{15}^2 \end{bmatrix}$$

$$\Theta^{(2)}_{[5 \times 6]}$$

$$\Theta^{(3)}_{[4 \times 6]}$$

$$\begin{pmatrix} \Theta_{20}^2 & \Theta_{21}^2 & \dots & \Theta_{25}^2 \\ \Theta_{50}^2 & \Theta_{51}^2 & \dots & \Theta_{55}^2 \end{pmatrix} \quad 5 \times 6$$

$$a^4 = (a_1^4, a_2^4, a_3^4, a_4^4)$$

$$y^{(w)} = (y_1, y_2, y_3, y_4)$$

$$\delta_j^4 = a_j^4 - y_j \quad j=1, 2, 3, 4$$

$$\underbrace{\delta^3}_{5 \times 1} = \underbrace{\left(\Theta^{(3)} \right)^T}_{4 \times 5} \underbrace{\delta^4}_{4 \times 1} \quad 5 \times 4 \cdot 4 \times 1 = 5 \times 1$$

$$\boxed{4 \times 5} \rightarrow \underline{5 \times 4}$$

$$(a_1^3, a_2^3, a_3^3, a_4^3, a_5^3)^T$$

$$\delta^3_{5 \times 1} =$$

$$\frac{\left(\begin{pmatrix} \delta^3 \end{pmatrix}^T \right)_{5 \times 4} \cdot \delta^4_{4 \times 1}}{\delta^3}$$

$$\downarrow \quad \uparrow$$

$$\cdot \quad \times \quad g'(z^3)$$

$$\delta^3_{5 \times 1}$$

$$y = f(x)$$

$$\Delta y = \frac{\partial f}{\partial x} \cdot \Delta x$$

$$\delta^3_{5 \times 1} = \left(\begin{pmatrix} \delta^3 \end{pmatrix}^T \right)_{5 \times 1} \cdot \delta^4_{5 \times 1} \cdot g'(z^3)_{5 \times 1}$$

$$5 \times 1$$

$$5 \times 1$$

$$5 \times 1$$

$$\begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix}$$

$$\cdot \times$$

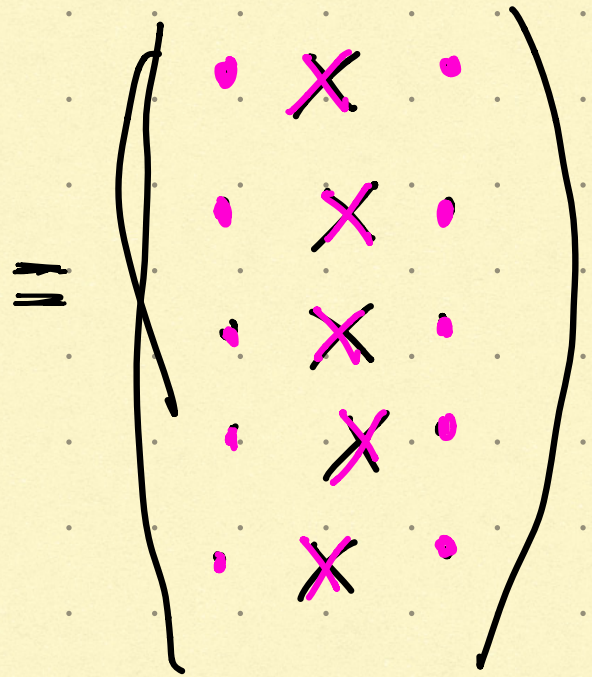
$$\begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix}$$

Hadamard product

$\odot$

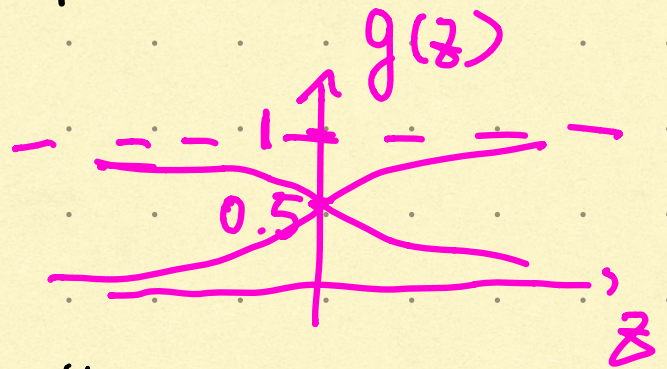
$\odot$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \odot \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \times 3 \\ 2 \times 4 \end{bmatrix} = \begin{bmatrix} 3 \\ 8 \end{bmatrix}$$

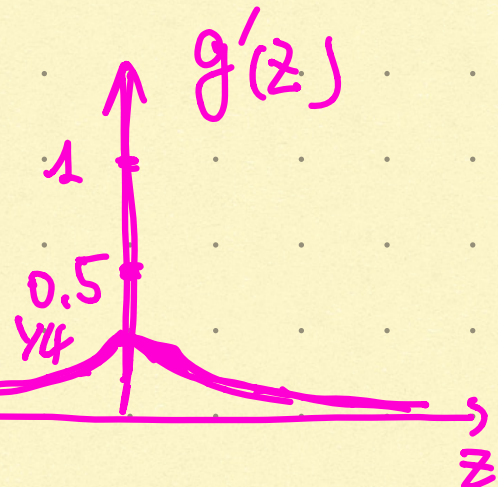


$$\delta^2 = \underbrace{(\Theta^2)^T}_{5 \times 1} \cdot \delta^3 \odot \underbrace{g'(z^2)}$$

$$g(z) = \frac{1}{1 + e^{-\theta x}}$$



$$\begin{aligned} g'(z) &= g(z)g(-z) \quad \text{logistic} \\ &= g(z)(1 - g(z)) \end{aligned}$$



once saturated,
learning slowly

$$\frac{\partial J}{\partial \theta_{12}^{2 \sim 1}} = a_2^2 \cdot \delta_1^3$$

$\swarrow \quad \searrow$
 $i \quad j$

$$\theta = \theta - \alpha \frac{\partial J}{\partial \theta}$$

$$\frac{\partial J}{\partial \theta_{..}^2} = \frac{\partial J}{\partial z^3} \left(\frac{\partial z^3}{\partial \theta_{..}^2} \right)$$

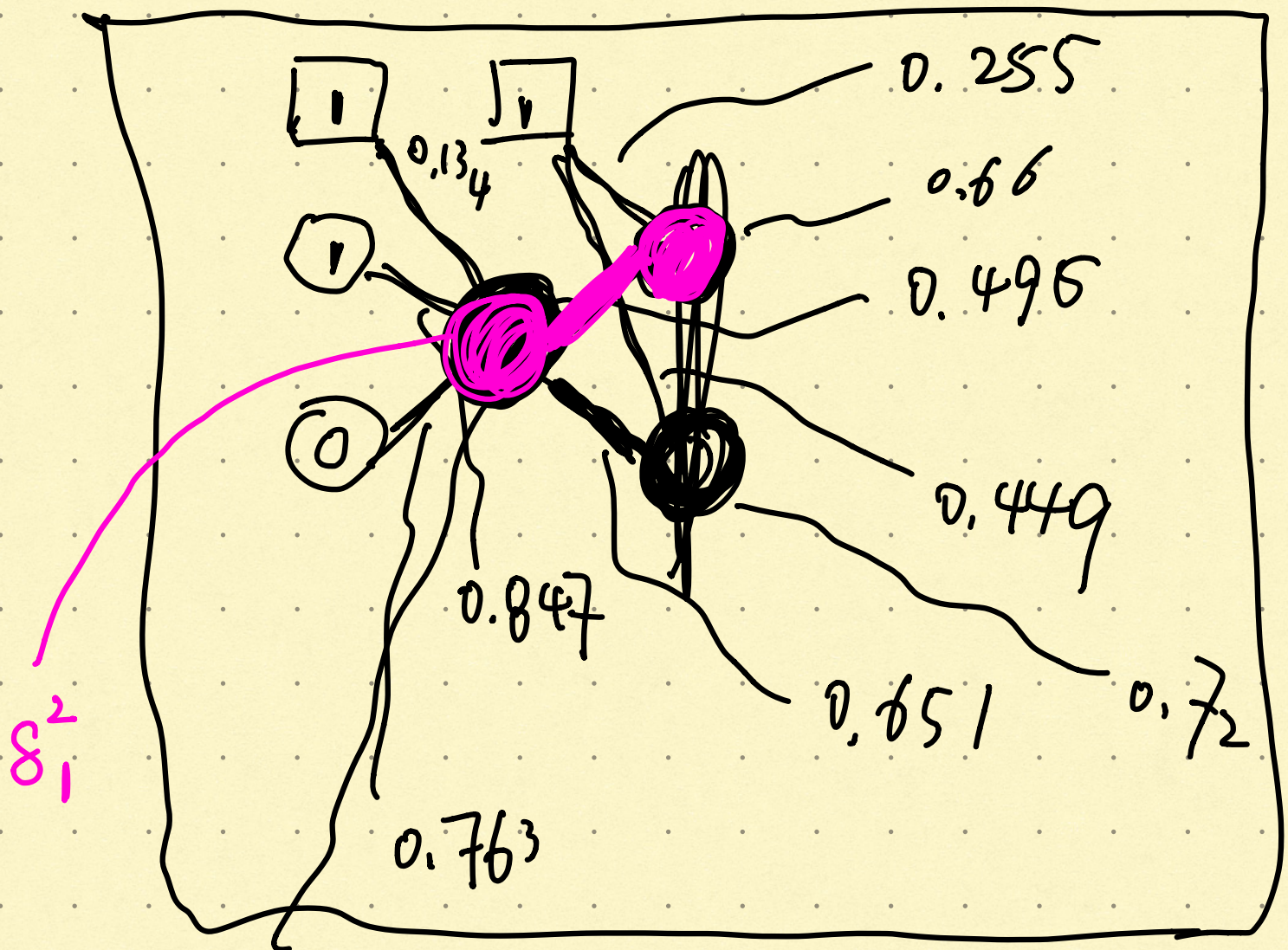
$\swarrow \quad \searrow$
 $\delta_0^3 \quad a_0^2$

$$\delta^3 = \Theta^2 \cdot Q^2 \rightarrow$$

$$= \begin{bmatrix} \Theta_{10}^2 & \Theta_{11}^2 & \dots & \Theta_{15}^2 \\ \vdots & \vdots & \ddots & \vdots \\ \Theta_{50}^2 & \Theta_{51}^2 & \dots & \Theta_{55}^2 \end{bmatrix}_{5 \times 6} \cdot \begin{bmatrix} Q_0^2 \\ Q_1^2 \\ Q_2^2 \\ \vdots \\ Q_5^2 \end{bmatrix}$$

$$\delta^2 = (\Theta^2)^T \delta^3 \cdot * g'(z^2)$$

Take an explicit example :



$$Z = \theta \cdot X$$

$$a = g(z) = \frac{1}{1 + e^{-z}}$$

$$a_1^{(2)} = \frac{1}{1 + e^{-(\theta_{10}' + \theta_{11}' x_1 + \theta_{12}' x_2)}}$$

$\downarrow \quad \quad \downarrow \quad \downarrow \quad \downarrow$
 $0.1343 \quad 0.847 \quad 0.76$

$$= \frac{1}{1 + e^{-(0.1343 + 0.847 \cdot 0.72736)}}$$

$$a_1^{(3)} = \frac{1}{1 + e^{-(\theta_{10}^2 + \theta_{11}^2 a_1^{(2)})}}$$

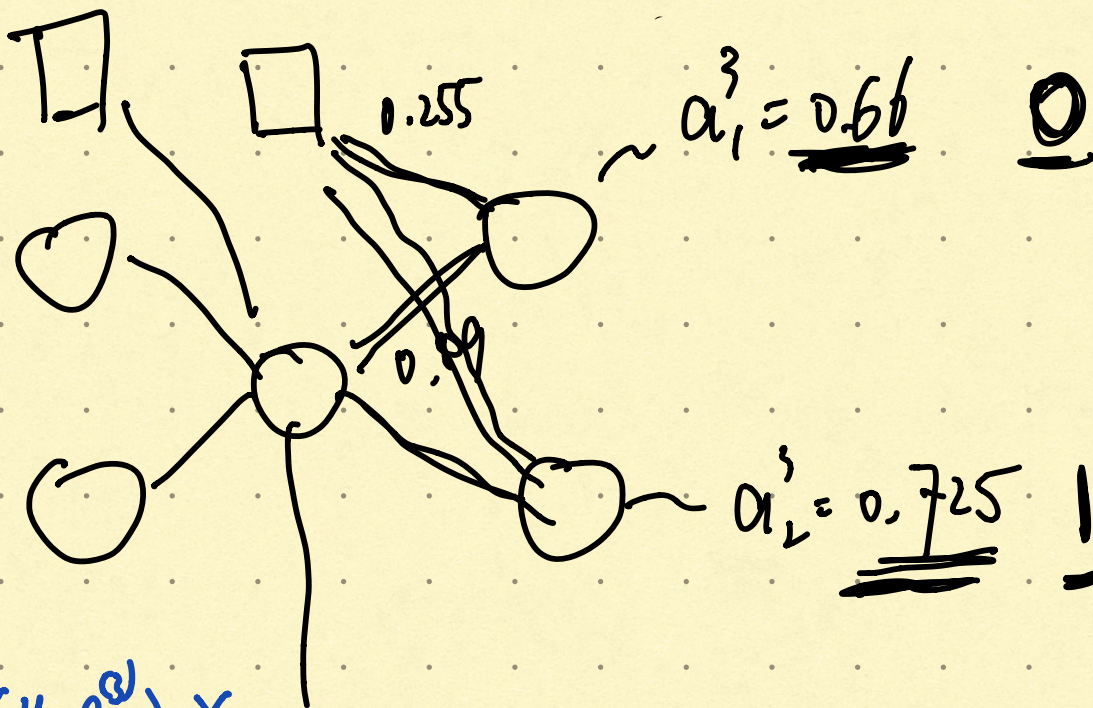
$$= \frac{1}{1 + e^{-(12.255 + 0.496)}}$$

$$= 0.66 \dots$$

$$a_2^{(3)} = \frac{1}{1 + e^{-(\theta_{20}^2 + \theta_{21}^2 a_1^2)}}$$

$$= \frac{1}{1 + e^{-(0.449 + 0.6516 \cdot 0.72736)}}$$

$$= 0.72 \dots$$



$$\delta^{(3)} = (y - a^{(3)}) \cdot \frac{1}{g'(a^{(3)})} \quad a_1^3 = 0.71$$

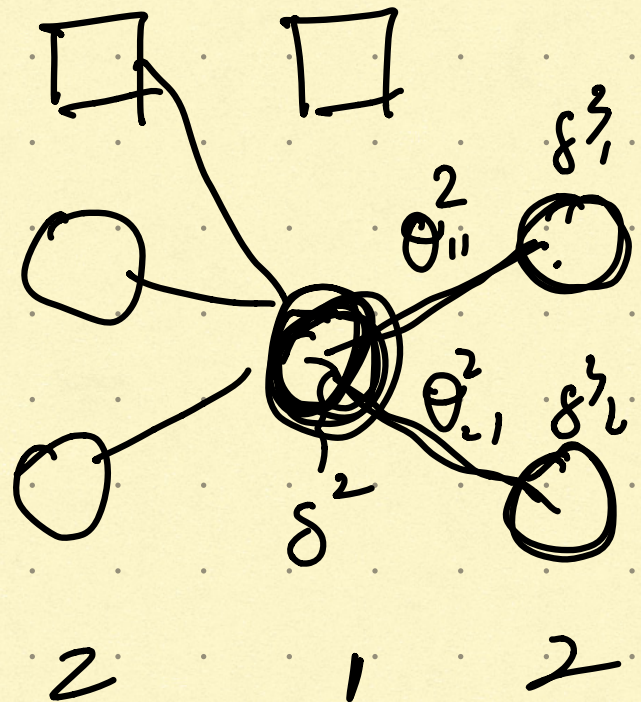
$$\delta^{(3)} \begin{pmatrix} \delta_1^{(3)} \\ \delta_2^{(3)} \end{pmatrix} = \begin{pmatrix} -0.66 \cdot 0.66 \cdot (1 - 0.66) = -0.148 \\ 0.235 \cdot 0.725 \cdot 0.235 = 0.0547 \end{pmatrix}$$

$$\tilde{\delta}^2 = (\theta^2)^T \cdot \delta^3 \quad 2 \times 2 \quad 2 \times 1$$

$$= \begin{pmatrix} \theta_{10}^2 & \theta_{20}^2 \\ \theta_{11}^2 & \theta_{21}^2 \end{pmatrix} \begin{pmatrix} \delta_1^3 \\ \delta_2^3 \end{pmatrix} = \begin{pmatrix} \theta_{10}^2 \delta_1^3 + \theta_{20}^2 \delta_2^3 \\ \theta_{11}^2 \delta_1^3 + \theta_{21}^2 \delta_2^3 \end{pmatrix}$$

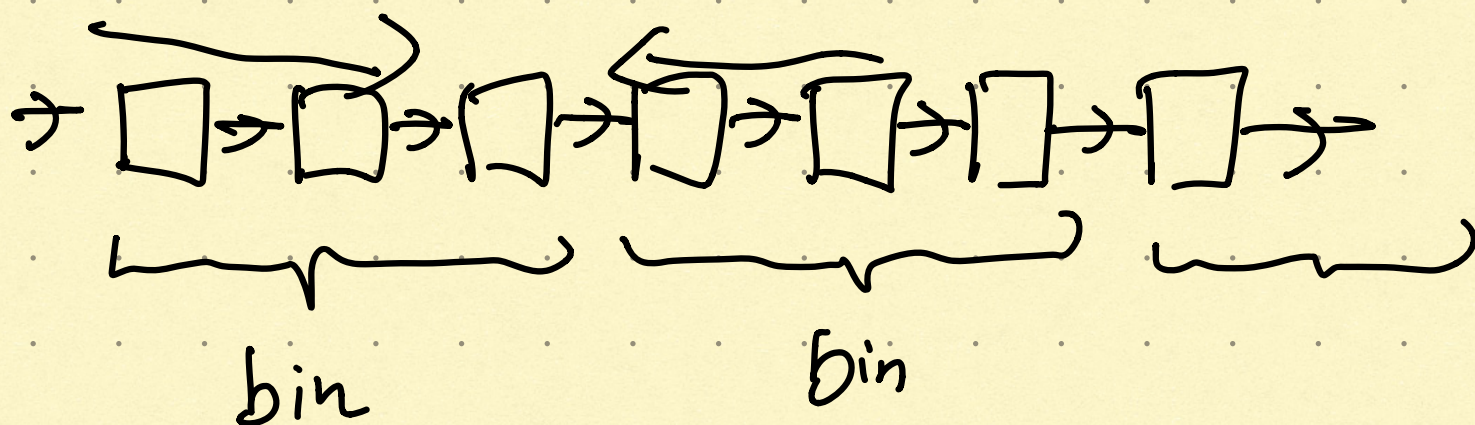
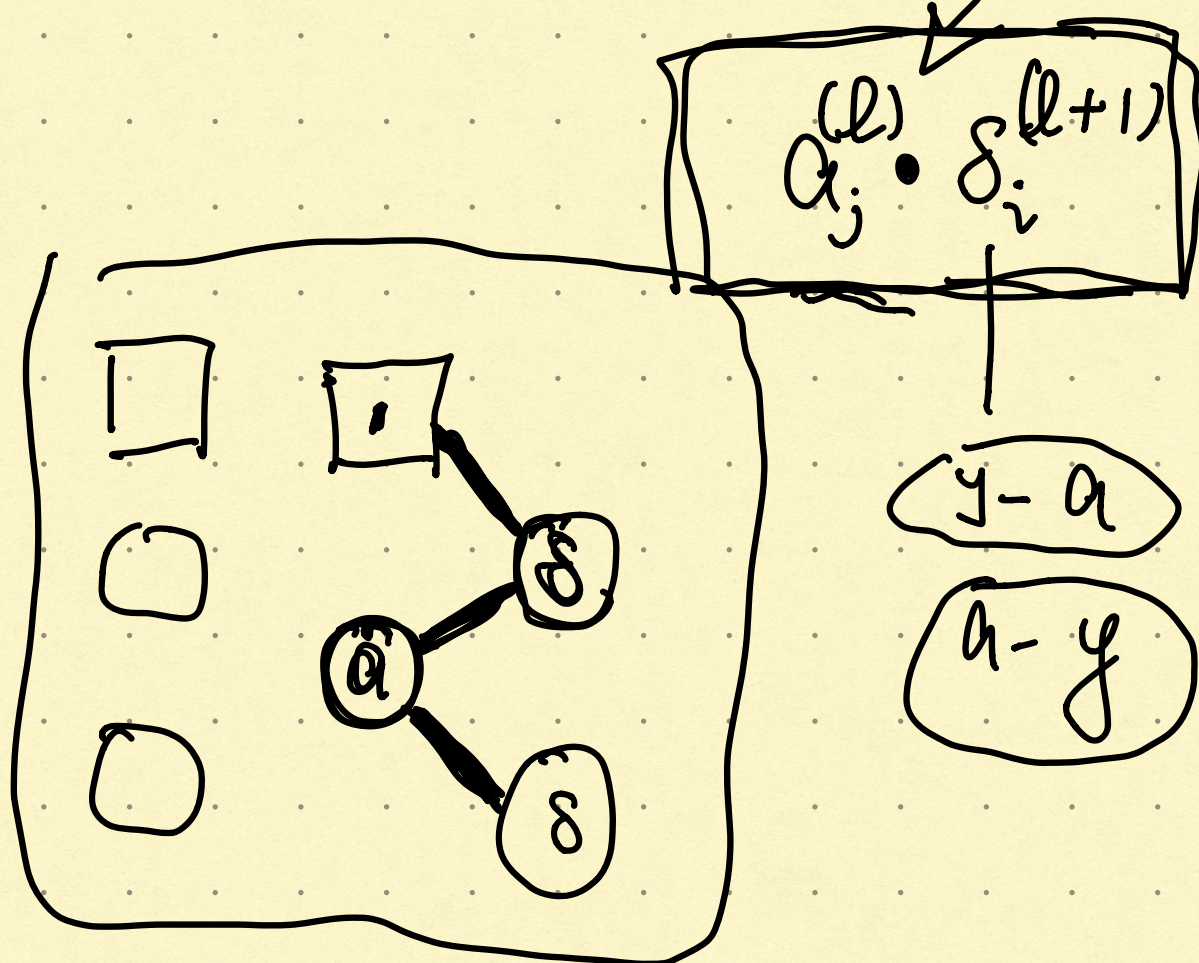
$\underbrace{\hspace{10em}}_{0,44} \quad \underbrace{\hspace{10em}}_{0,65}$

$$\theta^2 = \begin{pmatrix} \theta_{10}^2 & \theta_{11}^2 \\ \theta_{20}^2 & \theta_{21}^2 \end{pmatrix}$$



$$\delta^2 = (\theta^2)^T \cdot \delta^3 \cdot \underline{\underline{g'(z)}}$$

$$\theta^{new} \approx \theta^{old} - \alpha \cdot \frac{\partial J}{\partial \theta}$$



epoch

epoch

epoch

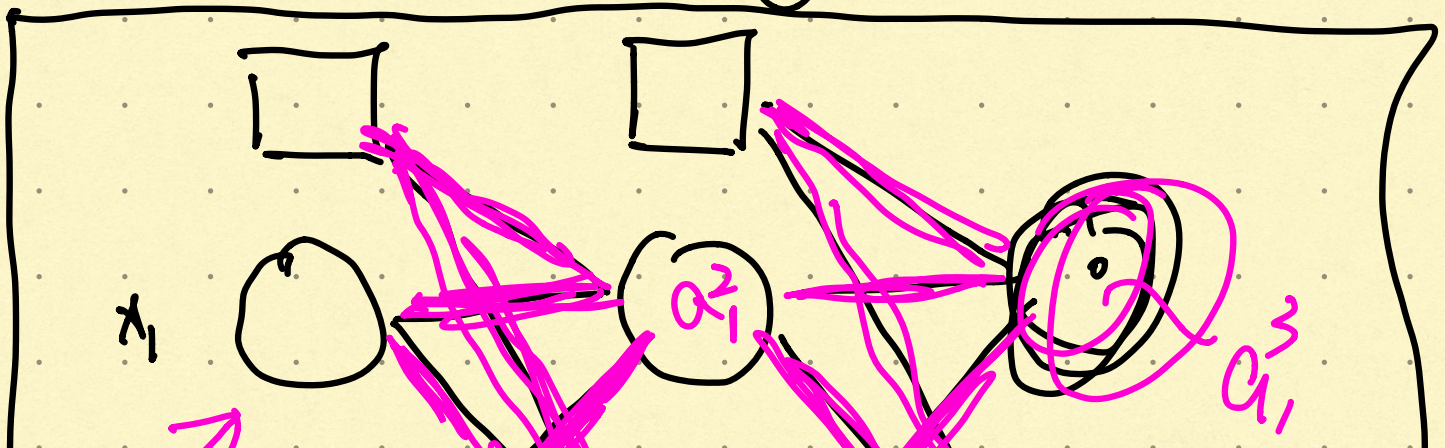
$$\{(\underline{x}^1, y^1), (x^2, y^2) \dots (x^m, y^m)\}$$

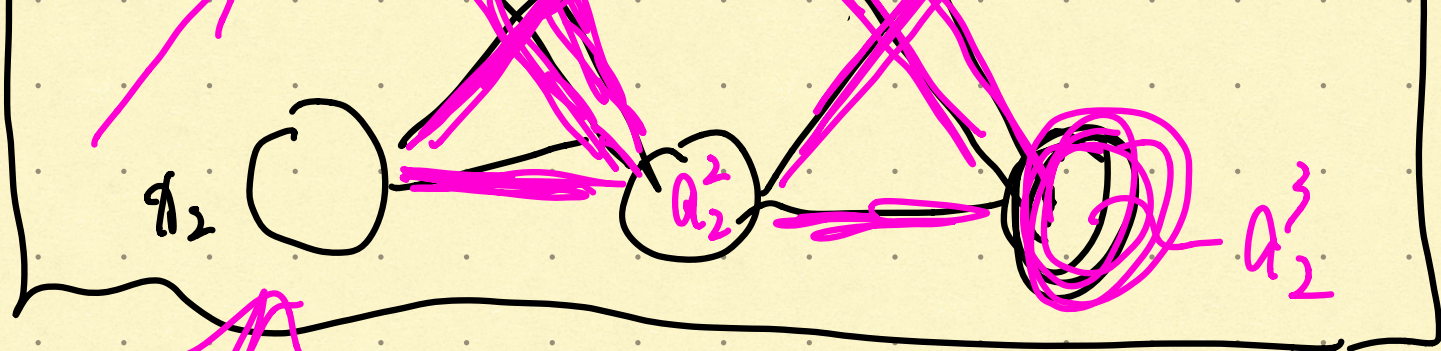


1, 2, 3

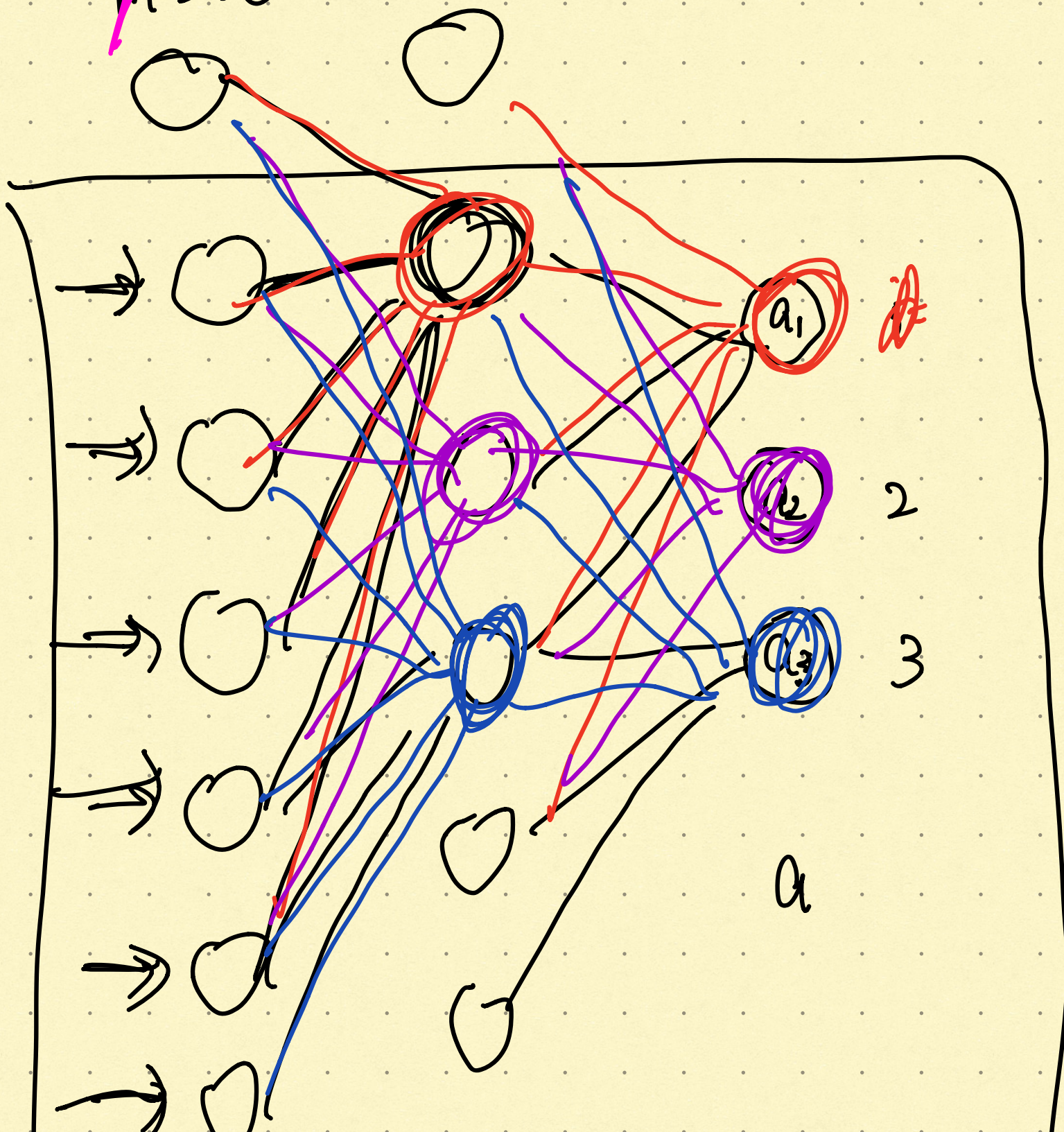
$$\begin{aligned} 1 &= [1, 0, 0] \\ 2 &= [0, 1, 0] \\ 3 &= [0, 0, 1] \end{aligned}$$

$$a = \frac{1}{1 + e^{-x}} \in (0, 1)$$





$m=10$



→ 0

3

7

5

MNIST

$$28 \times 28 = 784$$

60,000

$[0, 1, 2, \dots, 255]$

$[0, 1, 2, \dots, 9]$

784

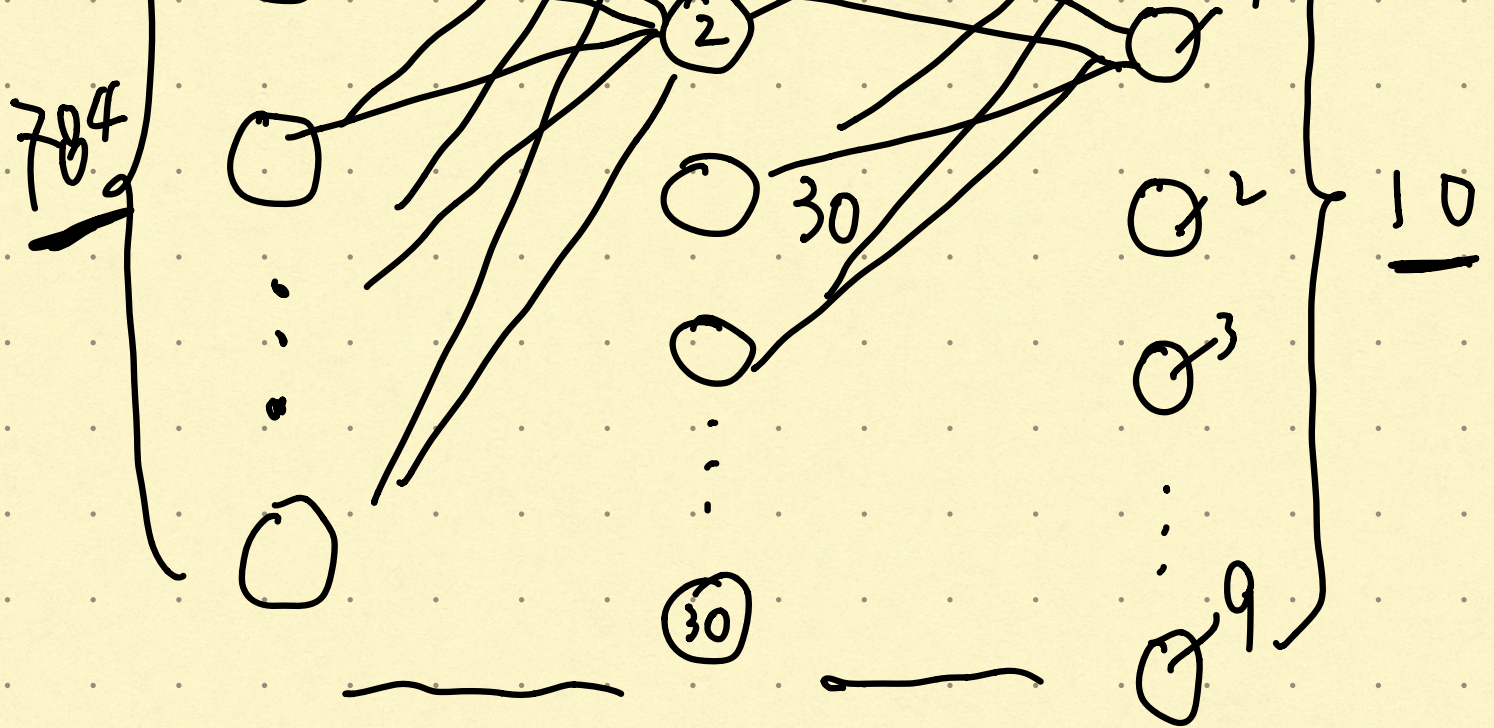
10

60,000

$x_i \in [0, \dots, 255]$

$$a = \frac{1}{1 + e^{-z}}$$





input

$$\begin{matrix} (1) \\ \Theta \\ 30 \times 784 \end{matrix}$$

||

23520

+

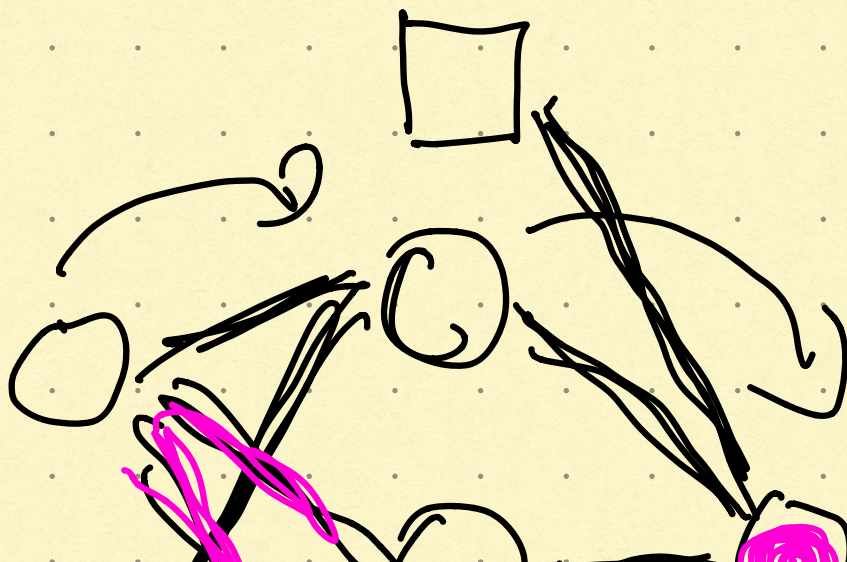
output

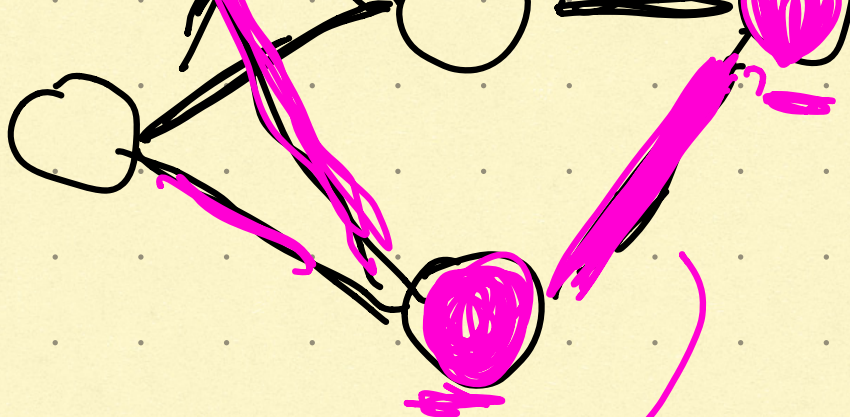
$$\begin{matrix} (2) \\ \Theta \\ 10 \times 30 \end{matrix}$$

||

310

= 23830





$\theta^{(1)}$



$\theta^{(2)}_{1 \times 4}$

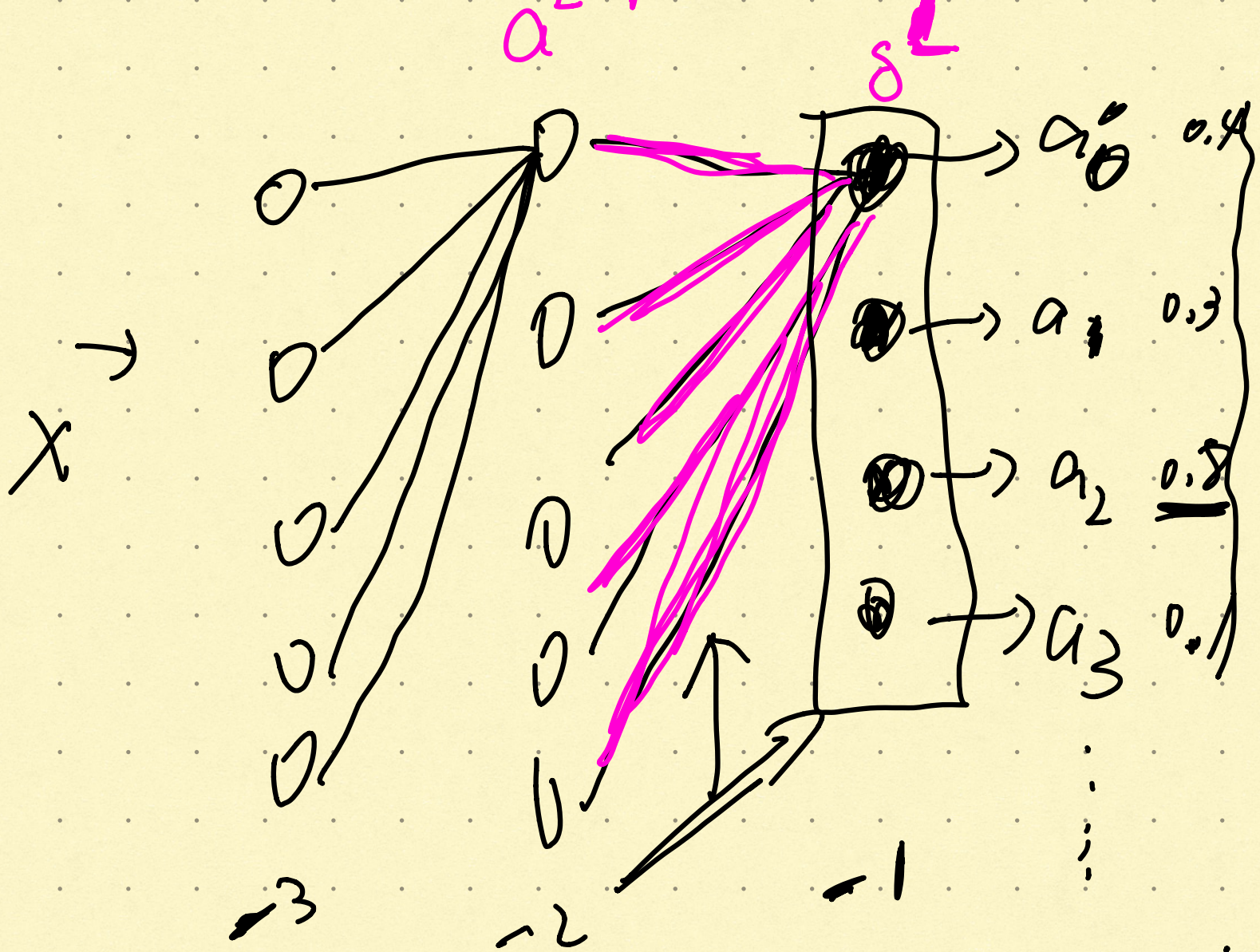
$\begin{bmatrix} \theta^{(2)}_{10} \\ \theta^{(2)}_{11} \\ \theta^{(2)}_{12} \\ \theta^{(2)}_{13} \end{bmatrix}$

$$\frac{\partial J}{\partial \theta} = \underline{a} \cdot \underline{\delta}$$

$$\delta^L = a^L - y$$

$$\delta = \underline{(a^L - y) \cdot g'(z)}$$

1-1



$$\sigma'(z)$$

$$g'(z)$$

$$y \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$$

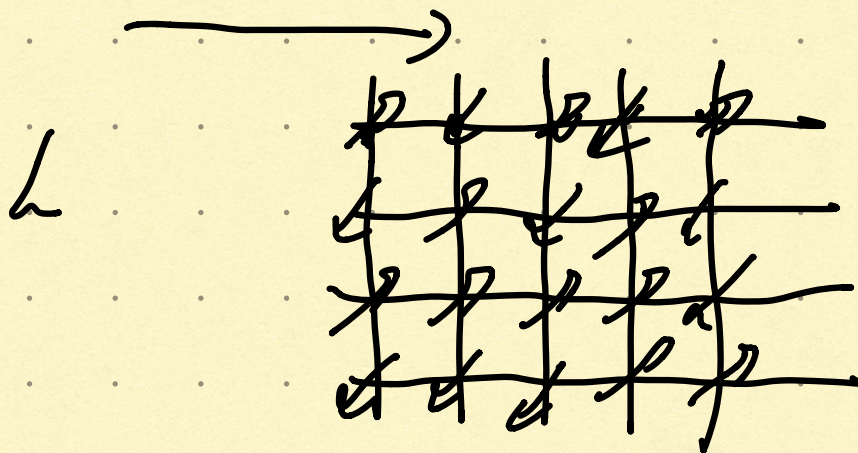
$$\delta^{(l)} = \Theta^T \cdot \delta^{(l+1)}$$

$$g(z) = \frac{1}{1 + e^{-z}}$$

2D Ising

8x8, 10x10, 16x16, 32x32

128x128



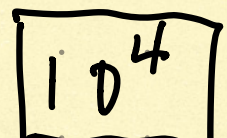
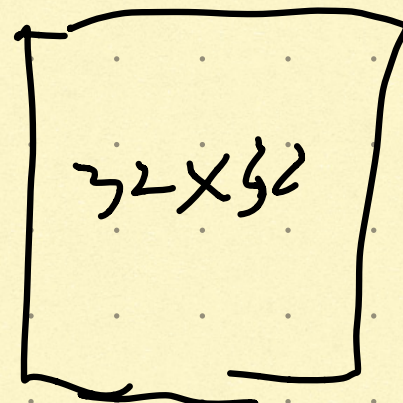
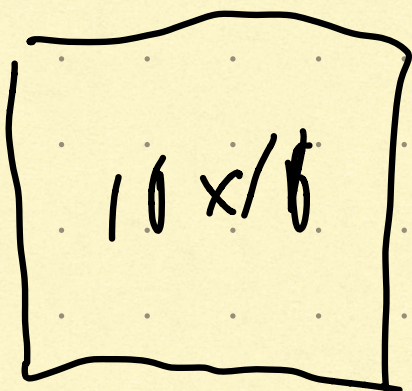
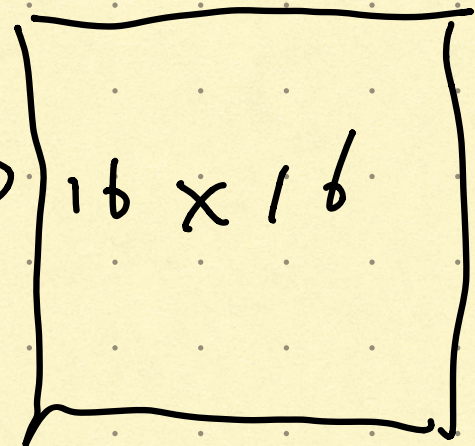
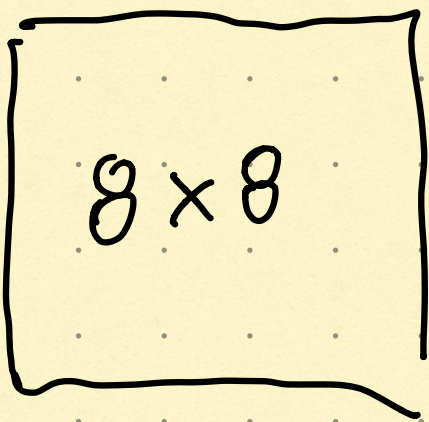
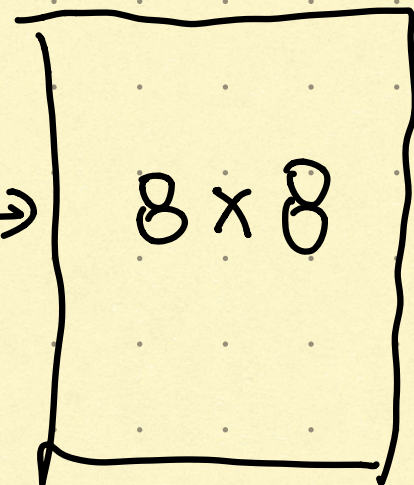
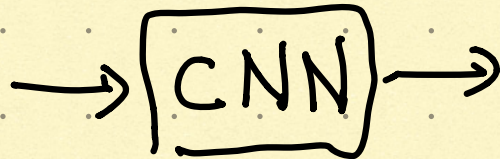
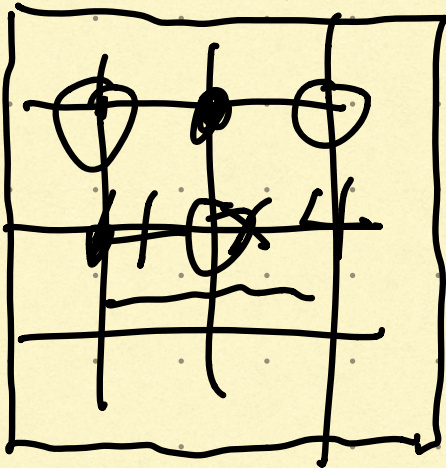
$$Z = \sum_{\{C\}} e^{-\frac{1}{T} E(C)} C$$

$E(C)$

$$e^{-\frac{1}{T} \cdot E(C)}$$

$$L \times L \propto \underline{L^2}$$

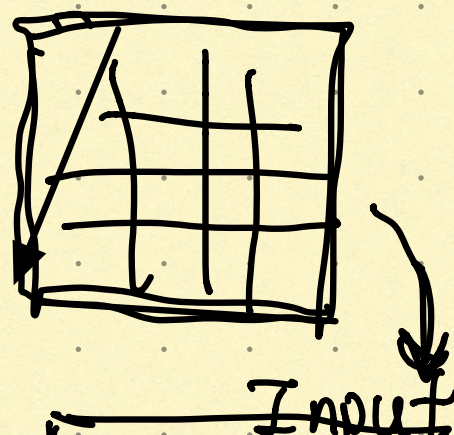
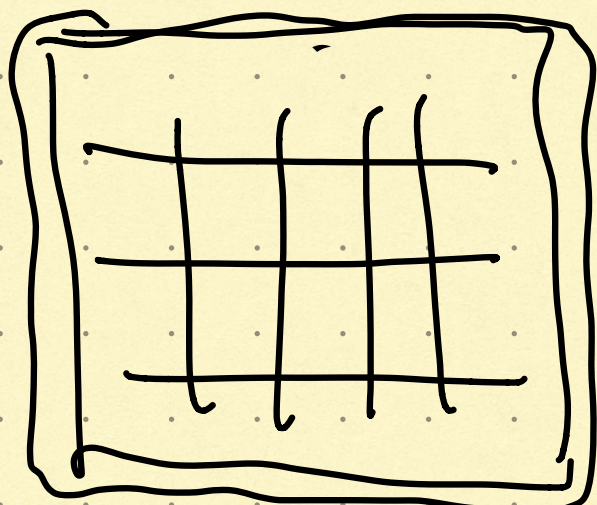
4x4

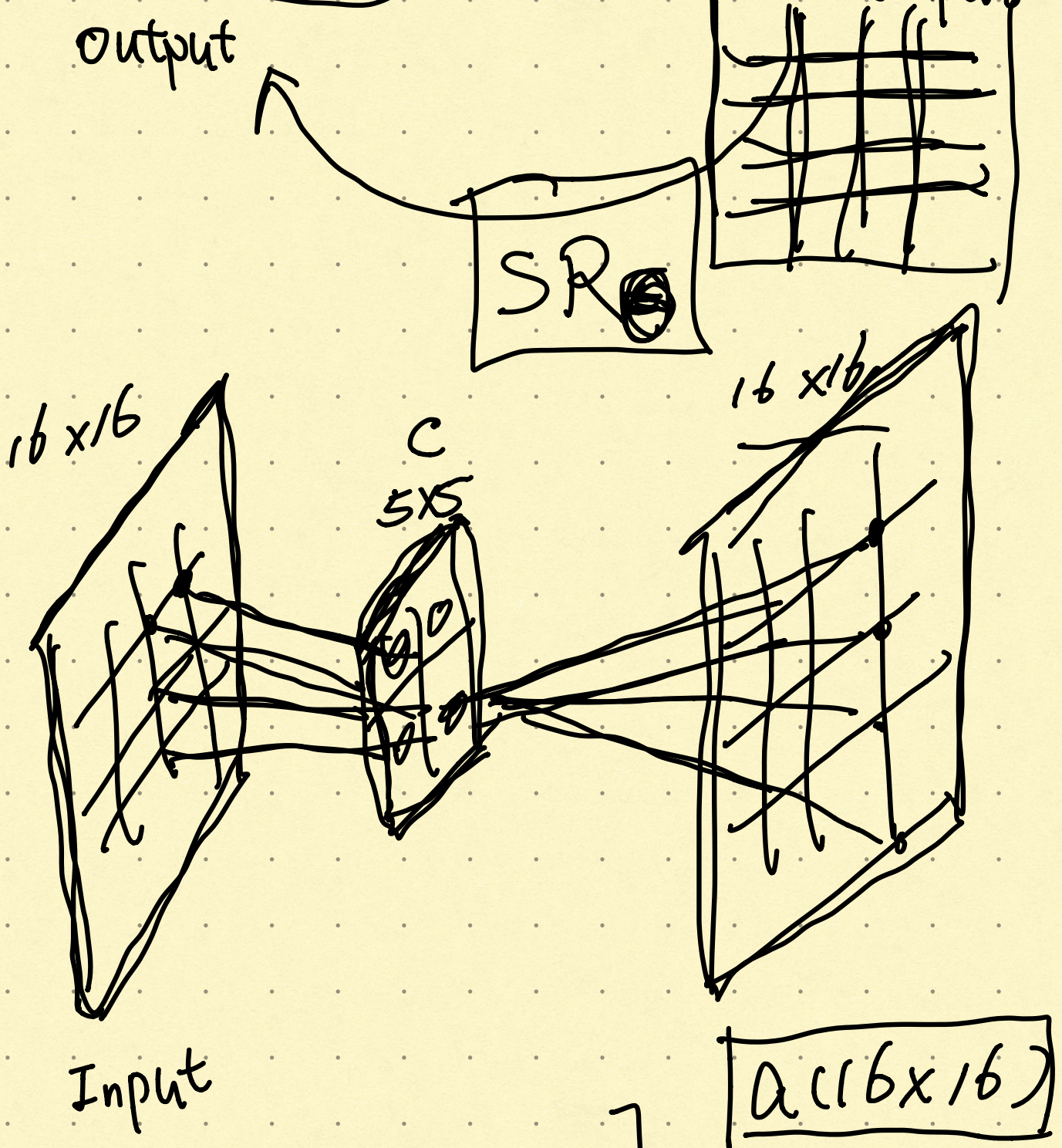


m, E
 c, X



$\uparrow$
 $MC \ 16 \times 16 \xrightarrow{(MR)} \underline{8 \times 8}$





$$a \in [0, 1]$$

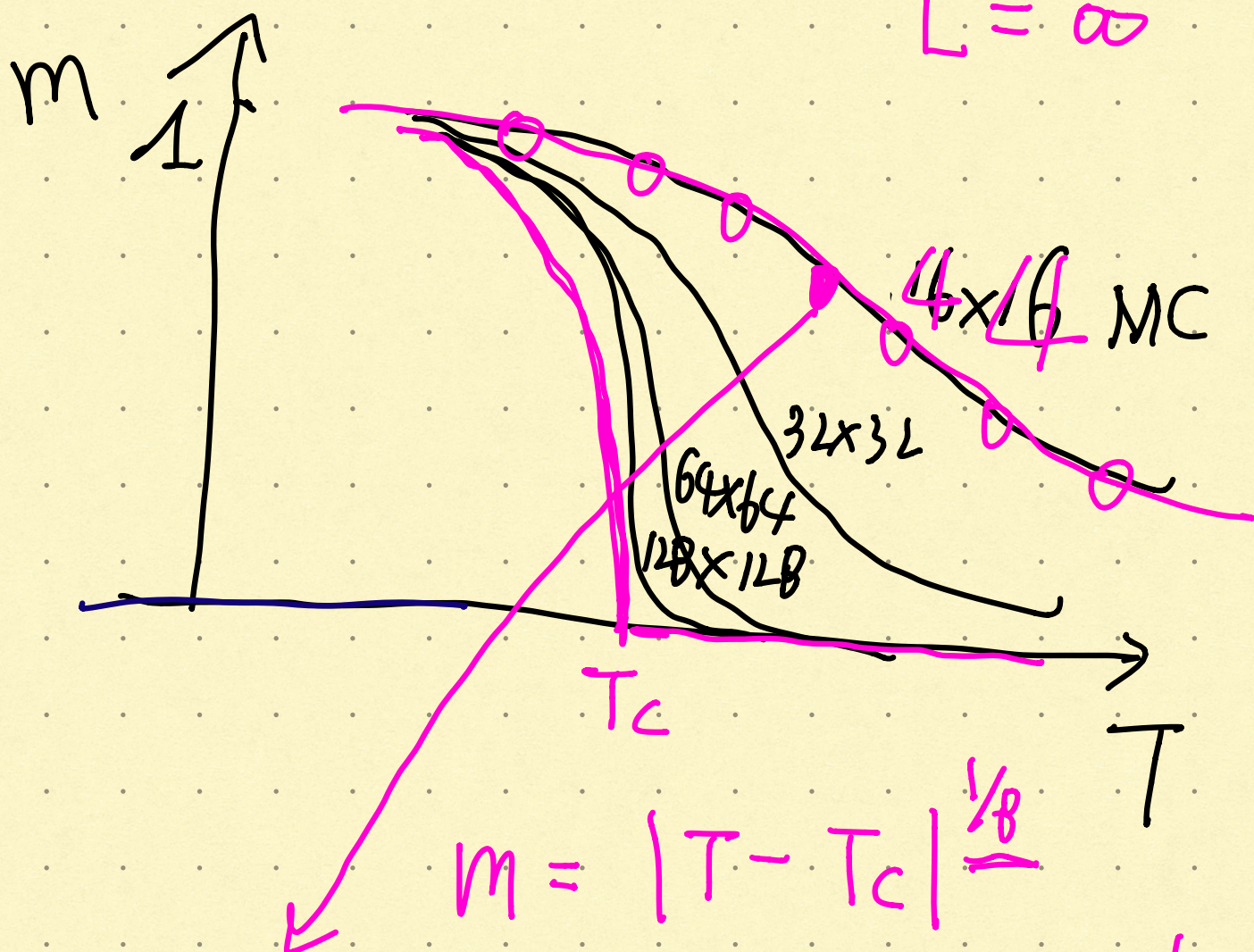
↓

$$a \in [-1, 1]$$

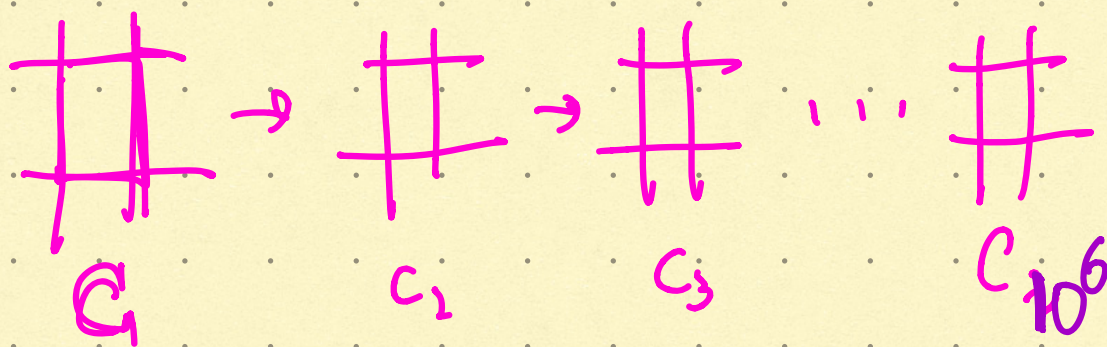
$$\frac{1}{1 + e^{-\theta \cdot x}}$$

$$2 \cdot \left(a - \frac{1}{2} \right)$$

$$(a_i - y_i)^2$$



$$\beta = \frac{1}{8} = 0,125$$



$$E = - \sum_{\langle i,j \rangle} S_i^z S_j^z$$

$$C = \langle E^2 \rangle - \langle E \rangle^2$$

$$\chi^2 = \langle M^2 \rangle - \langle |M| \rangle^2$$

$$E(c_1) \quad E(c_2) \quad E(c_3)$$

$$\underbrace{\langle E \rangle^2}_{\neq} = \frac{1}{3} \sum_{i=1}^3 E(c_i)$$

$$\underbrace{\langle E^2 \rangle} = \frac{1}{3} \sum_{i=1}^3 E^2(c_i)$$

